IN THE SPECIFICATION:

Page 16, first full paragraph, please amend as follows:

FIG. 5 shows a condition of the head arm 25 unloaded to the parking position, where the coil arm 26 engages the inertial arm 7. When the head arm 25 is in the parking position, the tab 35 of the suspension arm 32 is held by the ramp block 6. The disk 1 rests. Then, when the disk drive system starts operation, the head arm 25 is loaded ~~form~~ from the parking position so as to move the slider 4 on the surface of the disk 1 which starts rotational operation and the slider 4 is further moved to the desired data track on the basis of the servo data read by the head element (not shown) of the slider 4. FIG. 6 shows a condition just before the slider 4 comes close to the disk 1 (or just after coming apart from the disk 1), where the engagement between the coil arm 26 and inertial arm 7 is released.

Page 19, fourth full paragraph, please amend as follows:

When the disk drive system starts operation, the unshown controller actuates the spindle motor 2 to rotate the disk 1. Then, the driving current is applied to the coil 51 of the voice coil motor 23, the head arm 25 is loaded ~~form~~ from the parking position so as to move the slider 4 on the surface of the disk 1 which starts rotational operation and the slider 4 is further moved to the desired data track on the basis of the servo data read by the head element (not shown) of the slider 4. The wind receiver 7a formed on the inertial arm 7 receives the force of air flow produced at the same time as the rotation of the disk 1, and the inertial arm 7 itself is clockwise energized, and its position is defined by the casing 10.

Page 23, first full paragraph, please amend as follows:

The inertial arm 7 is counterclockwise energized by the second attractable member 9 attracted by the permanent magnet 55, and the actuator 22 is held in the parking position. Then,

when the disk drive system starts operation, the head arm 25 is loaded ~~form~~ from the parking position so as to move the slider 4 on the surface of the disk 1 which starts rotational operation and the slider 4 is further moved to the desired data track on the basis of the servo data read by the head element (not shown) of the slider 4.